Low-Rank Approximation of Kernel Matrices

Leopold Cambier

ICME, Stanford University

February 21, 2017

Integral equations

$$\int_X K(x,y)u(x)dx = f(y)$$

for given $K : X \times Y \to \mathbb{R}$, $f : Y \to \mathbb{R}$ and unknown $u : X \to \mathbb{R}$. Discretization gives

$$\sum_{i} K(x_i, y_j) u(x_i) = f(y_j)$$

Typical situation of BEM:

- X, Y are 2 parts of a 3D mesh
- May or may not be well-separated
- For instance,

$$K(x,y) = \frac{1}{\|x-y\|_2}$$

Motivation

When X and Y are well-separated, $K(x, y) = \frac{1}{\|x-y\|}$ is smooth and hence low-rank.



The problem

Given $X = \{x_1, \ldots, x_M\}$, $Y = \{y_1, \ldots, y_N\}$ and $K : X \times Y \to \mathbb{R}$, build a low-rank representation of $K_{ij} = K(x_i, y_j)$, i.e.

$$K \approx USV^{\top}$$

for $U \in \mathbb{R}^{M \times r}$, $V \in \mathbb{R}^{N \times r}$, $S \in \mathbb{R}^{r \times r}$.

Outline

Motivation

- 2 Low-Rank Kernel Approximation
- 8 Multivariate Polynomial Interpolation

4 Mappings

- 6 Numerical Results
 - Plates
 - Ellipsoid
 - Torus



Low-Rank Kernel Approximation

Motivatio



Multivariate Polynomial Interpolation

Mappings

5 Numerical Results

- Plates
- Ellipsoid
- Torus



Naive Solution

Naive idea

- Compute $K_{ij} = K(x_i, y_j) \mathcal{O}(MN)$
- Rank-revealing QR up to $\mathcal{O}(MNr)$

Bottleneck is $\mathcal{O}(MN)$ complexity.

Main Idea

Main idea

• Assume we are given

$$K(x,y) \approx \sum_{p=1}^{r} u_p(x) v_p(y)$$

• Then we immediately have

$$\mathcal{K}_{ij} \approx \sum_{p=1}^{r} u_p(x_i) v_p(y_j) = \sum_{p=1}^{r} u_{ip} v_{jp}$$

• How to compute $u_p(x)$ and $v_p(y)$?

The Answer

Interpolation !

Quick Review

Given a function $f: X \subset \mathbb{R}^d \to \mathbb{R}$ we can write

$$f(x) \approx \bar{f}(x) = \sum_{k=1}^{K} f(\bar{x}_k) T_k(x)$$

where x_k are interpolation nodes and T_k Lagrange basis functions, i.e.

$$T_k(\bar{x}_k) = 1, T_k(\bar{x}_i) = 0$$
 for $i \neq k$.

This directly implies (interpolation)

$$f(\bar{x}_k) = \bar{f}(\bar{x}_k).$$

Low-Rank Kernel Approximation

Given this, write

$$\begin{split} \mathcal{K}(x,y) &\approx \sum_{k=1}^{K} R_k(x) \mathcal{K}(\bar{x}_k,y) \\ &\approx \sum_{k=1}^{K} R_k(x) \sum_{l=1}^{L} T_l(y) \mathcal{K}(\bar{x}_k,\bar{y}_l) \\ &= \sum_{k=1}^{K} \sum_{l=1}^{L} R_k(x) \mathcal{K}(\bar{x}_k,\bar{y}_l) T_l(y) \\ &= \bar{\mathcal{K}}(x,y) \end{split}$$

We have an interpolation scheme on $X \times Y$ since

$$\bar{K}(\bar{x}_k, \bar{y}_l) = K(\bar{x}_k, \bar{y}_l).$$

Low-Rank Kernel Approximation

$$\bar{K}(x,y) = \sum_{k=1}^{K} \sum_{l=1}^{L} R_k(x) K(\bar{x}_k, \bar{y}_l) T_l(y)$$

=
$$\begin{bmatrix} | & | \\ R_1(x) & \dots & R_K(x) \\ | & | \end{bmatrix} \begin{bmatrix} K(\bar{x}_1, \bar{y}_1) & \dots & K(\bar{x}_1, \bar{y}_L) \\ \vdots & \vdots \\ K(\bar{x}_K, \bar{y}_1) & \dots & K(\bar{x}_K, \bar{y}_L) \end{bmatrix} \begin{bmatrix} -T_1(y)^\top - \\ \vdots \\ -T_L(y)^\top - \end{bmatrix}$$

rank $r_0 = \min(K, L)$

Given such representation, complexity becomes

$$\mathcal{O}\left(MK + KL + LN\right) \approx \mathcal{O}\left(r_0n\right)$$

versus

$$\mathcal{O}(MKr) \approx \mathcal{O}(rn^2)$$

before.

Recompression

Given

$$\bar{K} = RKT^{ op}$$
 rank $\bar{K} = r_0$

we further recompress \bar{K} as

$$\begin{split} \bar{K} &= (Q_R R_R) K (Q_T R_T)^\top \\ &= Q_R (R_R K R_T^\top) Q_T^\top \\ &= Q_R U_K S_K V_K^\top Q_T^\top \\ &= (Q_R U_K) S_K (Q_T V_K)^\top \\ &= U S V^\top \end{split}$$

where rank $\bar{K} = r_1$. This requires $\approx \mathcal{O}(nr_0r_1) + \mathcal{O}(r_0^2r_1)$ work.

One Thing Left Unanswered

Interpolation

How to obtain the (multivariate) interpolation ?

Multivariate Polynomial Interpolation

Motivation



8 Multivariate Polynomial Interpolation

Mappings

5 Numerical Results

- Plates
- Ellipsoid
- Torus



Univariate Polynomial Interpolation

- The best way to interpolate a smooth function f on [a, b] using polynomials is to use Chebyshev-like type of nodes that cluster to the boundary
- E.g.

$$ar{x}_k = rac{a+b}{2} + rac{b-a}{2}\cos\left(rac{2k-1}{2n}\pi
ight) \quad k = 1,\ldots,n$$

• Using barycentric formula (for stability), this implies

$$f(x) \approx \bar{f}(x) = \sum_{k=1}^{n} f(\bar{x}_k) \underbrace{\frac{\bar{w}_k}{x - \bar{x}_k}}_{= J_{j=1} \frac{\bar{w}_j}{x - \bar{x}_j}}$$

with

$$ar{w}_j = rac{1}{\prod_{k
eq j} (ar{x}_j - ar{x}_k)}$$

Multivariate Polynomial Interpolation

If $X = I_1 \times \cdots \times I_d$ where $I_i = [a_i, b_i]$ then use a sequence of univariate interpolation rules

$$f(x) \approx \bar{f}(x) = \sum_{k_1=1}^{K_1} \cdots \sum_{k_d=1}^{K_d} T_{k_1}(x_1) \dots T_{k_d}(x_d) f(\bar{x}_1, \dots, \bar{x}_d)$$

Mappings

Motivation

- 2 Low-Rank Kernel Approximation
 - Multivariate Polynomial Interpolation

4 Mappings

- 5 Numerical Results
 - Plates
 - Ellipsoid
 - Torus



Mappings

Mappings

Basic idea

Find a mapping $X \subset \mathbb{R}^d \to R$ such that

$$R = I_1 \times \cdots \times I_{d'}$$

and such that R is "small"

Mapping 1: Box

Find a box aligned with the data $X = \{x_1, \ldots, x_M\}$ using PCA:

- Translate points to the origin $\tilde{x}_i = x_i c$ where c is the center
- Compute the axis of the box as the eigenvector of the covariance matrix $C_{ij} = \tilde{x}_i^\top \tilde{x}_j$
- Compute the length of each axis

Works well if points lie on planes (d' < d) or almost planar surfaces.

Mapping 2: Ellipsoid

Find an ellipsoid tightly fitting the data

In general

$$f(x) = (x - x_c)^\top A(x - x_c) = 1$$

- Find x_c by taking the mean of the data
- Find A by

$$V = \operatorname{argmin}_{\mathcal{A} = \mathcal{A}^{\top}} \sum_{i=1}^{n} \left((x_i - x_c)^{\top} \mathcal{A} (x_i - x_c) - 1 \right)^2$$

• $A = P \Lambda P^{\top}$ gives the axis (p_i) and the length $(\frac{1}{\sqrt{\lambda_i}})$ of the ellipsoid

• In 3*d*, use this to build a polar coordinate representation of the data, minimizing the range of every coordinate

Numerical Results

Motivation

- 2 Low-Rank Kernel Approximation
 - Multivariate Polynomial Interpolation

Mappings



- Plates
- Ellipsoid
- Torus



Algorithm

- Given
 - $K: X \times Y \to \mathbb{R}$,
 - $\{x_1,\ldots,x_M\} \subset X$ and $\{y_1,\ldots,y_N\} \subset Y$
 - Test points $\{\tilde{x}_1, \ldots, \tilde{x}_{M'}\} \subset X$ and $\{\tilde{y}_1, \ldots, \tilde{y}_{N'}\} \subset Y$
 - Mappings $M_x : X \to I_x^1 \times \cdots \times I_x^{d_x}$ and $M_y : Y \to I_y^1 \times \cdots \times I_y^{d_y}$
 - Tolerance δ
- Start with $n_x = [0, 0, \dots, 0] \in \mathbb{N}^{d_x}$ and $n_y = [0, 0, \dots, 0] \in \mathbb{N}^{d_y}$ and build \overline{K}_{n_x, n_y} interpolating $K(M_x^{-1}(\cdot), M_y^{-1}(\cdot))$.

• While $\epsilon > \delta$,

- For $z = \{x, y\}$ and for $i = 1, \dots, d_z$
 - Increase $n_z[i]$ by 1 and build temporary \bar{K}_{n_x,n_y}

•
$$\epsilon_{z,i} = \frac{\|\bar{K}_{n_x,n_y}(\tilde{x},\tilde{y}) - K(\tilde{x},\tilde{y})\|}{\|K(\tilde{x},\tilde{y})\|}$$

• Pick $(z, i) = \operatorname{argmin}_{z,i} \epsilon_{z,i}$

•
$$\epsilon = \epsilon_{z,i}$$

- $n_z[i] = n_z[i] + 1$, update \bar{K}_{n_x,n_y}
- This gives \bar{K}_{n_x,n_y} of rank r_0
- Recompress to get \bar{K}'_{n_x,n_y} of rank r_1 .

Experiments

- 2d and 3d geometries
- Multiple radial kernels
- Compare to optimal low-rank factorization (SVD)
- Re-compression (from rank r_0 to r_1) always brings the rank very close $(\sim 5 10\% \text{ max})$ to the optimal value (r) and is ommited in plots, where we show r_0 (before recompression, for usual method "Tensor" and more involved "Sparse Grids") and the optimal rank r
- Sparse Grids ideas (i.e. removing some well-choosen nodes from Tensor) also used

Parallel Plates: 1/r



Plates

Parallel Plates: Sparse Grids



Parallel Plates: $r^2 \log(r)$



Parallel Plates: $1/r^2$



Parallel Plates - Increasing the Distance: 1/r



Perpendicular Plates: 1/r



Perpendicular Plates: $\sqrt{1+r^2}$



45° Plates: 1/r



Plates

45° Plates: r^3



Ellipsoid

Ellipsoid 2d: 1/r



Ellipsoid 2d: $r^2 \log(r)$



Ellipsoid 3d: 1/r



Ellipsoid

Ellipsoid 3d: $\sqrt{1+r^2}$



Torus 2d: 1/*r*



 $50\times50=2500$ points per partition

Torus 2d - A: 1/*r*



Torus 2d - B: 1/*r*



Torus 2d - C: 1/*r*



Low-Rank Kernel Matrix Approximation

- Method to approximate kernel matrices
- Independant of the size of the matrix
- Independant of the geometry, ...
- but requires a tight parametrization of the surface
- Can be improved by removing some well selected nodes ("Sparse Grids")

References

- Berrut, Jean-Paul, and Lloyd N. Trefethen. "Barycentric lagrange interpolation." SIAM review 46.3 (2004): 501-517.
- 🔋 Kaarnioja, Vesa. "Smolyak quadrature." (2013). Master's Thesis



- 2 Low-Rank Kernel Approximation
- 8 Multivariate Polynomial Interpolation



- 6 Numerical Results
 - Plates
 - Ellipsoid
 - Torus



Parallel Plates: $\sqrt{1+r^2}$



Parallel Plates: r^3



Torus 2d - A: Accuracy



Torus 2d - B: Accuracy



Torus 2d - C: Accuracy

